

Isogeometric analysis and thermomechanical contact

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Introduction

Thermomechanical systems [1]

- Nonlinear thermoelastic material models
- Thermodynamically consistent formulation
- Energy-momentum consistent integration schemes

Thermomechanical contact and isogeometric analysis [2]

- Isogeometrical discretisation of bodies in contact
- Transient isogeometric thermomechanical contact and impact problems
- Application of Mortar concepts

First law of thermodynamics

- Lagrangian formulation of the first law

$$\dot{T} + \dot{E} = P^{\text{ext}} + Q$$

- Legendre transformation

$$E = \int_{B_0} e(\mathbf{C}, \eta) dV = \int_{B_0} \Psi(\mathbf{C}, \Theta) + \Theta \eta dV$$

- Energy balance equation

$$\int_{B_0} \underbrace{\dot{\varphi} \cdot \bar{\pi}}_T dV + \int_{B_0} \underbrace{\frac{1}{2} \mathbf{S} : \dot{\mathbf{C}} + \Theta \dot{\eta}}_E dV = \int_{\partial B_0} \underbrace{\dot{\varphi} \cdot \mathbf{T}}_{P^{\text{ext}}} dA + \int_{\partial B_0} \underbrace{\mathbf{Q} \cdot \mathbf{N}}_Q dA$$

- Time dependent deformation field

$$\varphi(\mathbf{X}, t) : B_0 \times \mathcal{I} \rightarrow \mathbb{R}^n$$

- Time dependent absolute temperature field

$$\theta(\mathbf{X}, t) : B_0 \times \mathcal{I} \rightarrow \mathbb{R}$$

- Virtual work of the multi-field system

$$\int_{B_0} \delta \varphi \cdot \bar{\pi} + \frac{1}{2} \mathbf{S} : \delta \mathbf{C} dV = \int_{\partial B_0^T} \delta \varphi \cdot \bar{\mathbf{T}} dA + \int_{B_0} \delta \varphi \cdot \bar{\mathbf{B}} dV$$

$$\int_{B_0} \delta \theta \dot{\eta} - \mathbf{Q} \cdot \text{Grad}(\delta \theta) dV = \int_{\partial B_0^Q} \delta \theta \bar{\mathbf{Q}} \cdot \mathbf{N} dA + \int_{B_0} \delta \theta \bar{R} dV$$

- Constitutive laws

$$\Sigma = 2 \frac{\partial \Psi}{\partial \mathbf{C}}, \quad \eta = - \frac{\partial \Psi}{\partial \theta}, \quad \mathbf{Q} = - \hat{\mathbf{K}}(\mathbf{C}, \theta) \nabla_{\mathbf{X}}(\theta)$$

Interface conditions

- Virtual work of the contact contributions

$$G_c^c = \int_{\partial B_0^{(1),c}} t_N \delta g_N + \mathbf{t}_T \cdot (\delta \mathbf{g}_T^e + \delta \mathbf{g}_T^s) dA$$

$$G_\theta^c = \int_{\partial B_0^{(1),c}} \delta \theta^{(1)} Q_c^{(1)} + \delta \theta^{(2)} Q_c^{(2)} dA$$

- Normal contact

$$g_N \leq 0, \quad t_N \geq 0, \quad t_N g_N = 0$$

- Tangential contact

$$\hat{\phi}_c := \|\mathbf{t}_T\| - \mu |t_N| \leq 0, \quad \zeta \geq 0, \quad \hat{\phi}_c \zeta = 0, \quad \dot{\mathbf{g}}_T^s = \zeta \frac{\mathbf{t}_T}{\|\mathbf{t}_T\|}$$

- Thermal contact

$$Q_c^{(1)} = \gamma^{(1)} \mathbf{t}_T \cdot \dot{\mathbf{g}}_T^s - k_\theta |t_N| \vartheta_c, \quad Q_c^{(2)} = \gamma^{(2)} \mathbf{t}_T \cdot \dot{\mathbf{g}}_T^s + k_\theta |t_N| \vartheta_c$$

- Local entropy production rate

$$\dot{\eta}_c = \frac{Q_c^{(1)}}{\theta_c^{(1)}} + \frac{Q_c^{(2)}}{\theta_c^{(2)}} \geq 0$$

Mortar method

- Lagrange multiplier field

$$\mathcal{M}^h = \{\delta \mathbf{t}^{(1),h} \in \mathcal{L}^2(\partial B_0^{(1),c} \cap \partial B_0^{(2),c})\}$$

- Discrete contact contributions

$$G_\varphi^{c,h} = \lambda_{N,A} \mathbf{n} \cdot \left[n^{AB} \delta \mathbf{q}_B^{(1)} - n^{AC} \delta \mathbf{q}_C^{(2)} \right]$$

$$+ \lambda_{T,A} \cdot (\mathbf{I} - \mathbf{n} \otimes \mathbf{n}) \left[n^{AB} \delta \mathbf{q}_B^{(1)} - n^{AC} \delta \mathbf{q}_C^{(2)} \right]$$

$$G_\theta^{c,h} = -\delta \Theta_A^{(1)} \left\{ \gamma_1 \lambda_{T,B} \cdot (\mathbf{I} - \mathbf{n} \otimes \mathbf{n}) \left[m^{ABC} \dot{\mathbf{q}}_C^{(1),s} - m^{ABD} \dot{\mathbf{q}}_D^{(2),s} \right] \right.$$

$$\left. - k_\theta |\lambda_{N,B}| \left[m^{ABC} \Theta_C^{(1)} - m^{ABD} \Theta_D^{(2)} \right] \right\}$$

$$- \delta \Theta_A^{(2)} \left\{ \gamma_2 \lambda_{T,B} \cdot (\mathbf{I} - \mathbf{n} \otimes \mathbf{n}) \left[\bar{m}^{ABC} \dot{\mathbf{q}}_C^{(1),s} - \bar{m}^{ABD} \dot{\mathbf{q}}_D^{(2),s} \right] \right.$$

$$\left. + k_\theta |\lambda_{N,B}| \left[\bar{m}^{ABC} \Theta_C^{(1)} - \bar{m}^{ABD} \Theta_D^{(2)} \right] \right\}$$

- Triple Mortar integrals

$$m^{ABC} = \int_{\partial B_0^{(1),c}} R^A(\xi^{(1)}) N^B(\xi^{(1)}) R^C(\xi^{(1)}) dA$$

$$m^{ABD} = \int_{\partial B_0^{(1),c}} R^A(\xi^{(1)}) N^B(\xi^{(1)}) R^D(\xi^{(2)}) dA$$

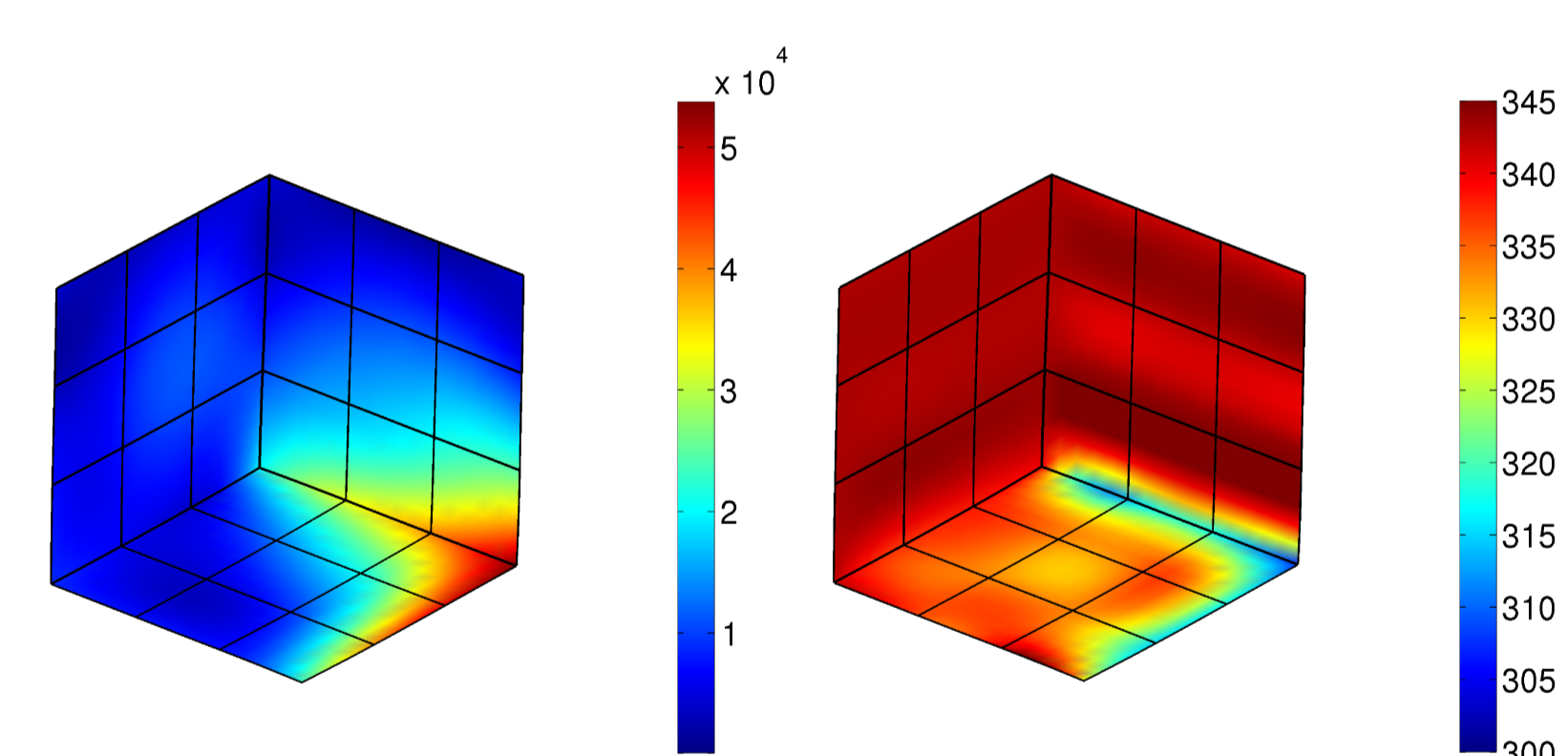
Numerical example

Non-linear and fully coupled Ogden material model

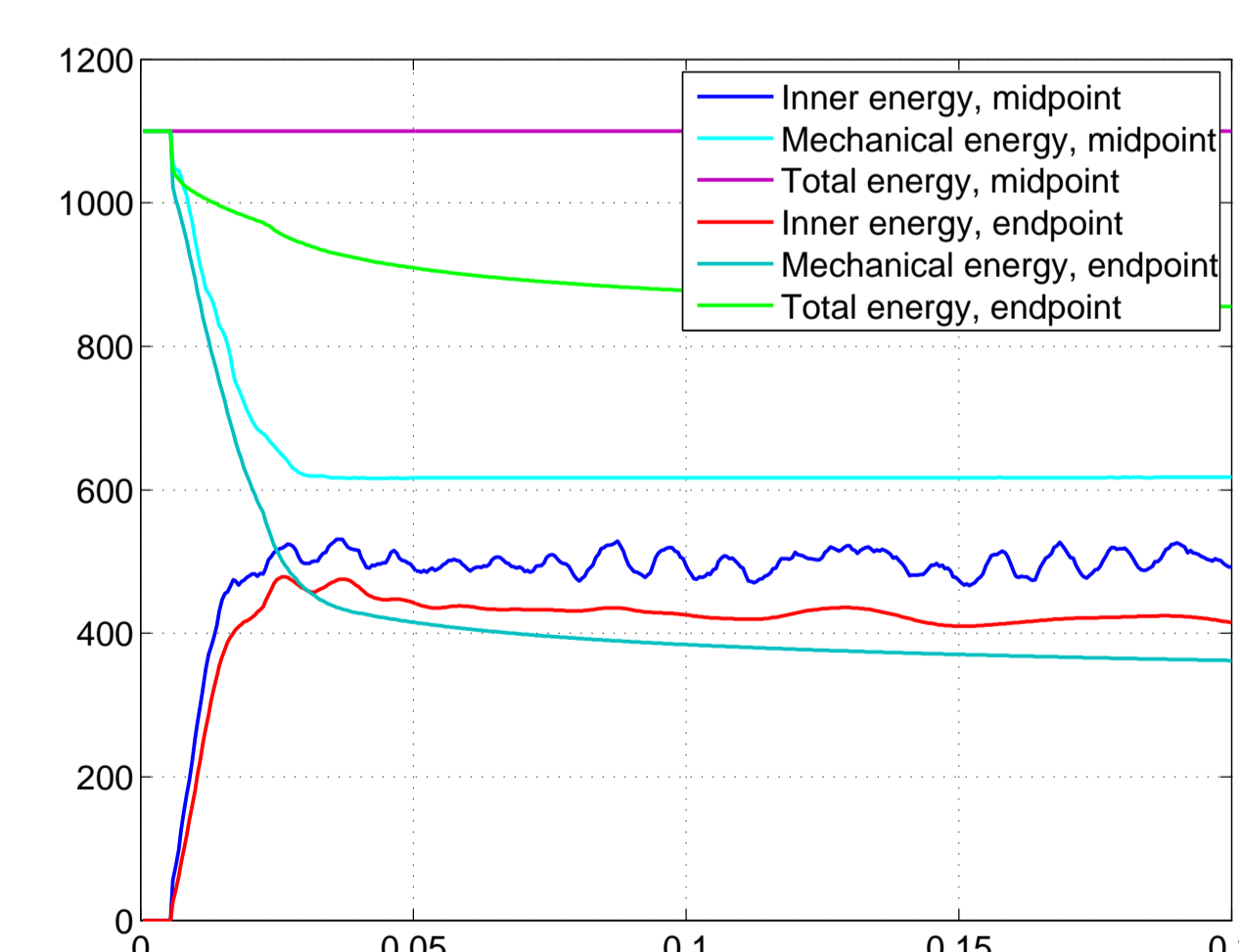
$$\Psi(\lambda_1, \lambda_2, \lambda_3, \theta) = \sum_{A=1}^3 \sum_{p=1}^3 \frac{\mu_p(\theta_0) \frac{\theta}{\theta_0}}{\alpha_p} \left(\tilde{\lambda}_A^{\alpha_p} - 1 \right) + \kappa(\theta_0) \frac{\theta}{\theta_0} \beta^{-2} \left(\beta \ln(J) + J^{-\beta} - 1 \right)$$

$$- 3\alpha_0 \kappa(\theta_0) \gamma^{-1} (J^\gamma - 1) (\theta - \theta_0) + c_0 (\theta - \theta_0 - \theta \ln(\theta/\theta_0))$$

Impact simulation



Von Mises stresses (left) and temperature (right) distribution.



Different energies for midpoint and endpoint rule.

References

- C. Hesch and P. Betsch. Energy-momentum consistent algorithms for dynamic thermomechanical problems - Application to mortar domain decomposition problems. *Int. J. Numer. Meth. Engng*, 86:1277–1302, 2011.
- M. Dittmann, M. Franke, İ. Temizer and C. Hesch. Isogeometric Analysis and thermomechanical Mortar contact problems. *Comput. Methods Appl. Mech. Engrg.*, 274:192–212, 2014